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to $F = ma$ if $\dot{m} = 0$. But if $m = m(t)$ (e.g. in rocket science) then the form with p is correct. General theorems governing differential equations guarantee that if we are given r and \dot{r} at an initial time $t = t_0$, we can integrate equation (1.1) to determine $r(t)$ for all t (as long as F remains finite). This is the goal of classical dynamics. { 2

Classical Dynamics - DAMTP

David Tong -- Cambridge Lecture Notes on Classical Dynamics. " So few went to hear him, and fewer understood him, that oftimes he did, for want of hearers, read to the walls. He usually stayed about half an hour; when he had no auditors he commonly returned in a quarter of that time."

David Tong -- Cambridge Lecture Notes on Classical Dynamics

Principles of Dynamics , D.T. Greenwood (2nd edition Prentice & Hall 1988). Also good are: Classical Mechanics , T.W.B. Kibble and F.H. Berkshire (Imperial College Press) Classical Mechanics , V.D. Barger and M.G. Olsson (McGaw-Hill 1995). (limited coverage of normal modes).

Handout 1 2006-7 v1 - University of Cambridge

Selected lecture notes and problems from Classical Dynamics (PHY 520), taught by Gerhard Müller at the University of Rhode Island. Some Relevant Textbooks and Monographs: H. Goldstein: Classical Mechanics. Addison Wesley, 1981. I. Percival and D. Richards: Introduction to Dynamics. Cambridge University Press, 1982.

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Solved Problems in Classical Mechanics $v(t) = \frac{dr(t)}{dt}$, (1) and the acceleration $a(t)$, which is the time rate of change of the velocity, $a(t) = \frac{dv(t)}{dt}$. (2) It follows from (1) and (2) that the acceleration is also the second derivative $a = \frac{d^2r}{dt^2}$. (3) Sometimes use is made of Newton's notation, where a dot denotes differentiation with

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This section aims to revise and summarise the approach of reference [1] and the results that are relevant to the full characterisation of arbitrary deterministic, classical processes. In ordinary dynamics, a process is a function that maps the state of a system at a given time to the state at a future time. Operationally, we can think of the state in the past as a 'preparation' and the one in ...

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An undamped driven harmonic oscillator satisfies the equation of motion $m(d^2x/dt^2 + \omega_0^2x) = F(t)$. The driving force $F(t) = F_0 \sin(\omega t)$ is switched on at $t = 0$. (a) Find $x(t)$ for $t > 0$ for the

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initial conditions $x = 0$ and $v = 0$ at $t = 0$.

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